## WMS: 1 I. Aims of Statistics:

- A. Probability is the study of relative proportions of random outcomes based on structure of generating process.
- B. Statistics is the inverse problem:
  - 1. Observe data generated by process
  - 2. Infer process.

WMS: 8.1

II. Estimation

A. Aim

- 1. Want to estimate some number  $\theta$  , called a parameter .
  - a. Fraction of population supporting a candidate
  - b. Population Average effect of some cholesterol-lowering medication.
  - c. Mass of an electron
- 2. Rule that gives estimate is called an estimator.
- 3. Want it based on some data.
  - WMS: 8.2, 8.4
- B. Preliminaries: What makes a good estimator
  - 1. Quantify what happens if you make a wrong decision
    - a. Suppose that you pay a penalty  $\,L(a,\theta)\,$  if your guess is  $a\,$  when the truth is  $\,\theta\,$ 
      - i. Penalty is called Loss function .
      - ii. Most typically,  $L(a,\theta) = (a-\theta)^2$ : Squared error loss.
- C. Typically, want rule that depends on data,  $\,\delta({m X})\,$ 
  - 1. Example
    - a. If  $X \sim {\mathcal B}{\mathrm{in}}(n,\theta)$  ,  $\delta(X)$  might be X/n

## Lecture 1

- iii. 
  $$\begin{split} R(\delta,\theta) &= (a\theta+b-\theta)^2+a^2\sigma^2 = \\ (a-1)^2\theta^2+2b(a-1)\theta+b^2+a^2\sigma^2 \end{split}$$
- iv. If  $a\neq 1$  maximum is  $\infty \Rightarrow$  choose a=1 , and risk is  $b^2+a^2\sigma^2 \Rightarrow$  choose b=0
- h. "Best" (ie, minimax) estimator might allow some bias in return for smaller variance WMS: 8.3

## D. Examples

- 1. Estimate of the range of a uniform distribution from the range of a sample
  - a.  $X_1, \ldots, X_n \sim \mathcal{U}[\alpha, \beta]$ , i.i.d..
  - b.  $X_{(1)}, \ldots, X_{(n)}$  are ordered values: order statistics.
  - c.  $\delta(\mathbf{X}) = X_{(n)} X_{(1)}$
  - d. Density of  $X_{(n)}$  is

$$n \frac{1}{\beta - \alpha} \left( \frac{y - \alpha}{\beta - \alpha} \right)^{n-1}$$

e. 
$$\mathbf{E} \left[ X_{(n)} \right]$$
 is  

$$= \int_{\alpha}^{\beta} yn \frac{1}{\beta - \alpha} \left( \frac{y - \alpha}{\beta - \alpha} \right)^{n-1} dy$$

$$= \int_{0}^{1} (\alpha + z(\beta - \alpha))nz^{n-1} dz$$

$$= n\alpha \int_{0}^{1} z^{n-1} dz + n(\beta - \alpha) \int_{0}^{1} z^{n} dz$$

$$= \alpha + \frac{n}{n+1}(\beta - \alpha)$$
f.  $\mathbf{E} \left[ Y_{(1)} \right] = -(-\beta + \frac{n}{n+1}(-\alpha - (-\beta)) = \beta - \frac{n}{n+1}(\beta - \alpha)$ 

- b. If  ${\pmb X}$  is a sample from a population with expectation  $\theta$  , then  $\delta({\pmb X})$  might be  $\bar{X}$
- c. If  ${\bm X}$  is a sample from a population with median  $\theta$  , then  $\delta({\bm X})$  might be sample median
- 2. Select estimator before wee see data.
  - a. Consider average of loss function P(S, 0) = P(S, 0)
  - $R(\delta, \theta) = E[L(\delta(\mathbf{X}), \theta)].$
  - b. R is called risk function .
    i. Risk function for squared error loss is called mean squared error (MSE) .
  - c. Review expectation
  - d. Let  $\mu = \operatorname{E} \left[ \delta(\boldsymbol{X}) \right]$
  - e.  $R(\delta, \theta)$  is variance plus bias squared.  $= E \left[ (\delta(\mathbf{X}) - \mu + \mu - \theta)^2 \right]$   $= E \left[ (\delta(\mathbf{X}) - \mu)^2 + 2(\delta(\mathbf{X}) - \mu)(\mu - \theta) + (\mu - \theta)^2 \right]$   $= E \left[ (\delta(\mathbf{X}) - \mu)^2 \right] + E \left[ 2(\delta(\mathbf{X}) - \mu)(\mu - \theta) \right]$   $+ E \left[ (\mu - \theta)^2 \right]$   $= Var \left[ \delta(\mathbf{X}) \right] + 2(\mu - \theta) E \left[ (\delta(\mathbf{X}) - \mu) \right] + (\mu - \theta)^2$ 
    - $= \operatorname{Var} \left[ \delta(\boldsymbol{X}) \right] + (\operatorname{E} \left[ \delta(\boldsymbol{X}) \right] \theta)^2$
  - f. We can often make the second part 0: i. If  $\mathop{\mathrm{E}}\nolimits[\delta({\boldsymbol{X}})]=\theta$ , then  $\delta({\boldsymbol{X}})$  is called unbiased. ii. and  $\mathop{\mathrm{E}}\nolimits[\delta({\boldsymbol{X}})]-\theta$  is called the bias.
  - g. We will see that unbiasedness does not completely specify the best estimator
    - i. Ex.:  $X \sim \mathcal{N}(\theta, \sigma^2)$  with  $\sigma$  known.

ii. 
$$\delta(X) = aX + b$$

g.  $E[\text{Range}] = \alpha - \beta + \frac{2n}{n+1}(\beta - \alpha) = e_n(\beta - \alpha)$  for  $e_n = \frac{n-1}{n+1}$ .

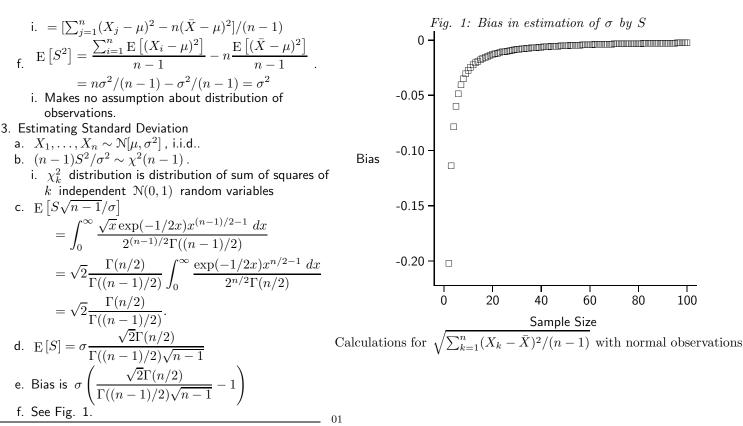
h. Bias is 
$$\frac{-2}{n+1}(\beta - \alpha)$$

- i. Almost unbiased.
  - $\lim_{n\to\infty} bias = 0$ .
- Called asymptotically unbiased .
- i. Hence to get unbiased estimator, use  $\frac{n+1}{n-1}$ Range.
- i. Let  $v_n = \operatorname{Var} \left[ X_{(n)} X_{(1)} \right] (\beta \alpha)^{-2}$ , which does not depend on  $\alpha$  or  $\beta$ .
- ii. MSE of  $\delta(\mathbf{X}) = a \text{Range}(\mathbf{X})$  is  $\{(ae_n 1)^2 + a^2 v_n\}(\beta \alpha)^2$
- iii. Differentiating, setting the derivative to zero, and solving for a gives  $a=e_n/(e_n^2+v_n)$  .
- iv. Since  $v_n>0$  , minimizing a leaves  $\delta({\boldsymbol X})$  with a slight bias.
- 2. Estimating variance

a. 
$$X_1, \dots, X_n$$
 i.i.d., expectation  $\mu$ , variance  $\sigma^2$ .  
b.  $\bar{X} = \sum_{j=1}^n X_j/n$   
c. Then  $\sum_{j=1}^n (X_j - \mu)^2$  is  
 $= \sum_{j=1}^n (X_j - \bar{X})^2 + \sum_{j=1}^n (\bar{X} - \mu)^2 + 2\sum_{j=1}^n (\bar{X} - \mu)(X_j - \bar{X})^2$   
 $= \sum_{j=1}^n (X_j - \bar{X})^2 + n(\bar{X} - \mu)^2$ .  
d.  $\sum_{j=1}^n (X_j - \bar{X})^2 = \sum_{j=1}^n (X_j - \mu)^2 - n(\mu - \bar{X})^2$   
e.  $S^2 = \sum_{j=1}^n (X_j - \bar{X})^2/(n-1)$ 

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5 Lecture 2



Lecture 2

7 Lecture 2

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